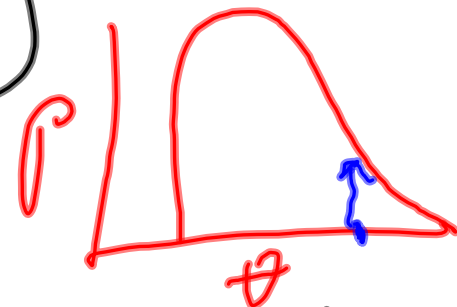


Bayesian Theory

Baye's Theorem



$$p(\theta/x) \propto \pi(\theta) \mathcal{L}(x/\theta)$$

$$p(\theta/x) = \frac{\pi(\theta) \mathcal{L}(x/\theta)}{\int_{\theta} \pi(\theta) \mathcal{L}(x/\theta) d\theta}$$

① Prior may prove uninformative
in a given case, if the
data are "overwhelming"
(but not if the likelihood shows
non-identifiability).

② IF the prior is influential,
it needs to be empirically
"true".

③ Every unknown or
"uncertain" demand must
be a parameter.

④ Every parameter must
have a prior
(i.e. appear in the joint prior)

PVA Retrospective Analysis with Measurement Error

Imagine that retrospective
analysis is based on
census trajectory where
there is census error

Consider Brownian Motion

PVA:

Environmental variation

in λ has a mean

and a std.

(ignore demographic
stochasticity)

r ($= \ln \lambda$)
 μ_r (mean of distribution
of environmental
variability - normal)

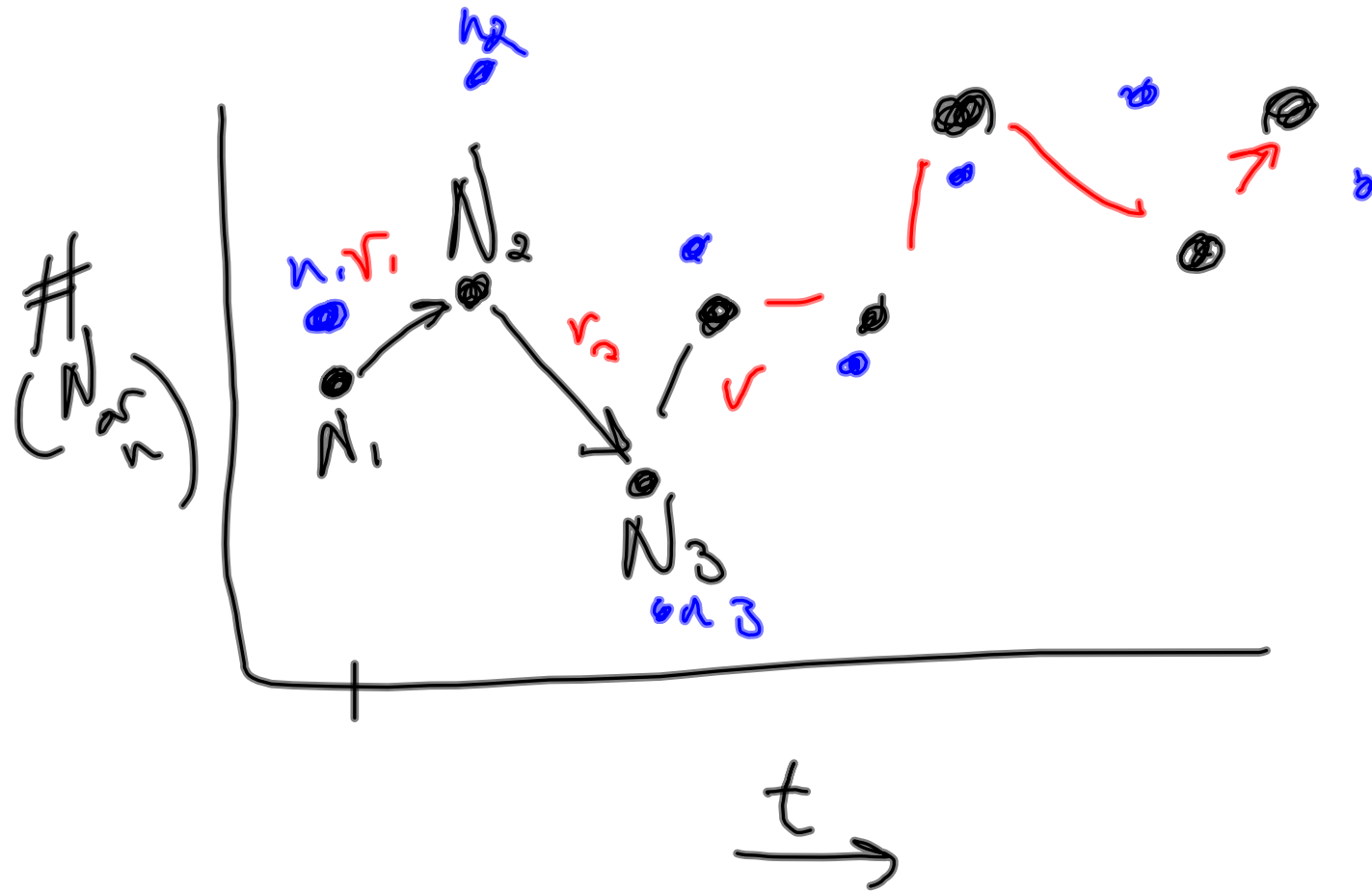
σ_r

N

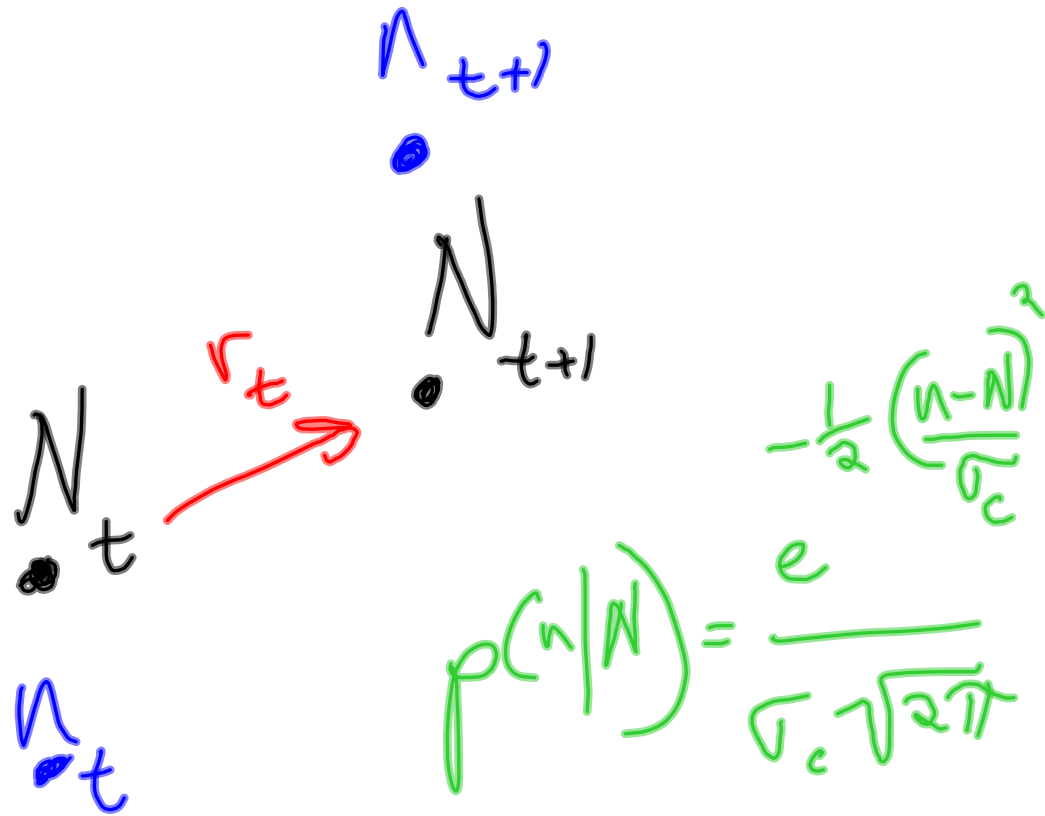
true population in
log space

n

observed census estimate
in log space



- state descriptor
- state equation
- observed



$$p(n|N) = \frac{e^{-\frac{1}{2} \left(\frac{n-N}{\sigma_c} \right)^2}}{\sigma_c \sqrt{2\pi}}$$

$\mathcal{L}(n | N)$ "Gaussian error distribution"

State equation $-\frac{1}{2} \left(\frac{N_{t+1} - \mu_r}{\sigma_r} \right)^2$

$$P(N_{t+1} | N_t) = \frac{e}{\sigma_r \sqrt{2\pi}}$$

Component of the prior

Other components of prior

$\Pi(\mu_r)$

'comparative empirical, literature'

$\Pi(\sigma_r)$
 $\Pi(N)$

'habitat'

Log Joint prior

$$\ln(\pi(\mu)) + \ln(\pi(\sigma^2)) + \sum_{j=1}^k \ln(\pi(N_j))$$

$$+ \sum_{j=1}^{k-1} -\frac{1}{2} \left(\frac{N_{j+1} - N_j - \mu_a}{\sigma_r} \right)^2$$

$$- (k-1) \ln(\sigma_r \sqrt{2\pi})$$

Log Joint Likelihood

$$\sum_{j=1}^k -\frac{1}{2} \left(\frac{y_j - \mu_j}{\sigma_c} \right)^2$$
$$- k \ln(\sigma_c \sqrt{2\pi})$$

Feed \log Joint prior
+ \log Joint likelihood
to MCMC

See if marginal posterior
for μ_r and σ_r differ
from their priors
(depend on K and σ_c)

Building in Density - Dependence

$$\mu_r = \mu(N)$$

$$\mu_r = a + bN$$

add a parameter
need priors for π_a π_b